Infrastructure Prototyping with Bolt and Vagrant

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From Hashicorp
  ○ Makers of Terraform, Vault, and others

Easy infrastructure prototyping
  ○ Define one or more VMs of any type with any arbitrary configuration
  ○ Unified configuration language for VirtualBox, libvirt, and others

https://vagrantup.com/
● From Puppet
  ○ Makers of, well, Puppet

● Orchestrates actions across systems
  ○ Can use any combination of commands, scripts, or even Puppet code
  ○ Flexible inventory, with support for custom plugins

https://puppet.com/open-source/bolt/
Getting Started

Bolt
https://puppet.com/docs/bolt/latest/bolt_installing.html

Vagrant
https://www.vagrantup.com/downloads

Vagrant provider

VirtualBox
https://www.virtualbox.org/wiki/Downloads
Building VMs

- Create an empty directory to work from
- `cd` into it
- Run `vagrant init centos/8`
  - Creates a `Vagrantfile` with a CentOS 8 VM configured

```ruby
Vagrant.configure("2") do |config|
  config.vm.box = "centos/8"
end
```

- Edit the `Vagrantfile` to add additional VMs
Building VMs

Example Vagrantfile:

```ruby
Vagrant.configure("2") do |config|
  config.vm.define "centos" do |centos|
    centos.vm.box = "centos/8"
    centos.vm.provider "virtualbox" do |vb|
      vb.memory = "1024"
    end
  end

  config.vm.define "windows" do |windows|
    windows.vm.box = "gusztavvargadr/windows-server"
    windows.vm.provider "virtualbox" do |vb|
      vb.memory = "1024"
    end
  end
end
```

To start the VMs, run `vagrant up`. 
Useful vagrant subcommands

- vagrant init
- vagrant up
- vagrant rsync
- vagrant provision
- vagrant reload
- vagrant halt
- vagrant destroy
- vagrant ssh
- vagrant status
- vagrant global-status
Setting up Bolt

$ bolt project init

or

$ bolt project init projectname

Creates two files

- bolt-project.yaml
- inventory.yaml
Adding the `bolt_vagrant` module

```
$ bolt module add dylanratcliffe-bolt_vagrant
```

- Updates `bolt-project.yaml`
- Creates a Bolt-managed `Puppetfile`
- Installs the module (plus any dependencies) in the `.modules` directory

https://forge.puppet.com/modules/dylanratcliffe/bolt_vagrant
Enabling `bolt_vagrant` inventory

- Add the following to `inventory.yaml`:
  ```yaml
  targets:
  - _plugin: task
    task: bolt_vagrant::targets
  ```

- Run `bolt inventory show -t all`
  - You should see `centos` and `windows` in the output.
Running ad-hoc commands

Run a command across all of our VMs:

$ bolt command run hostname -t all
Running scripts

Run arbitrary scripts against our VMs:

$ echo hostname > myscript.ps1

$ bolt script run myscript.ps1 -t all
Running tasks

Bolt tasks are scripts with some associated metadata that is used to specify script arguments, etc.

Several tasks are shipped with Bolt. You can see the current list with `bolt task show`.

To add additional tasks, either install additional Puppet modules that contain tasks or create a directory named `tasks` and drop in the necessary files.
Running tasks

tasks/hostname.json:

```json
{
  "puppet_task_version": 1,
  "supports_noop": false,
  "description": "Run hostname",
  "implementations": [
    { "name": "hostname.sh", "requirements": ["shell"] },
    { "name": "hostname.ps1", "requirements": ["powershell"] }
  ],
  "parameters": {}
}
```

tasks/hostname.sh:

```bash
#!/bin/sh
hostname
```

tasks/hostname.ps1:

```powershell
hostname
```
Running tasks

Once those files are in place, you can run the task on all nodes with the following command:

$ bolt task run demo::hostname -t all
Plans

- Plans can run a set of commands, scripts, tasks, or other plans in a set sequence on a list of targets.

- Bolt supports two different kinds of plans
  - Plans written in YAML
  - Plans written in the Puppet language
Writing Plans

Generate a new YAML plan template:

$ bolt plan new demo::hostname1

Generate a Puppet-language plan template:

$ bolt plan new demo::hostname2 --pp

Alternatively, add plan files in a directory named `plans` in the Bolt project
Plans

For `demo::hostname1`, we can modify `plans/hostname1.yaml` to look like this:

description: Run hostname via a YAML plan
parameters:
  targets:
    type: TargetSpec
    description: A list of targets to run actions on
    default: all
steps:
- message: Hello from demo::hostname1
- name: command_step
  command: hostname
  targets: $targets
return: $command_step
To get the same functionality out of `demo::hostname2`, modify `plans/hostname2.pp` to look like this:

```plaintext
plan demo::hostname2 (  
  TargetSpec $targets = 'all',
) {
  out::message('Hello from demo::hostname2')
  $command_result = run_command('hostname', $targets)
  return $command_result
}
```
Plans

You can run these plans with

$ bolt plan run demo::hostname1

or

$ bolt plan run demo::hostname2

Note that we do not need to supply a list of targets for either of these plans because they default to a target list of all.
Using a Bolt Plan for Provisioning

With a couple of minor tweaks to our `Vagrantfile`, we can use a Bolt plan for provisioning.

First, we need to enable an experimental Vagrant feature - `typed_triggers`. We can do this by adding the following line to the beginning of our `Vagrantfile`:

```env
ENV['VAGRANT_EXPERIMENTAL'] = 'typed_triggers'
```
Using a Bolt Plan for Provisioning

Next, we want to make sure that any Puppet modules that Bolt needs (like bolt_vagrant) are installed before we try to use them. Add the following to the `Vagrant.configure(2)` block:

```ruby
config.trigger.before [:up, :provision, :reload], type: :command do |trigger|
  trigger.info = 'Initializing bolt'
  trigger.run = { inline: 'bolt module install' }
end
```
Using a Bolt Plan for Provisioning

Finally, we want to run our plan after all of the VMs have started:

```hcl
config.trigger.after [:up, :provision, :reload], type: :command do
  trigger.info = 'Running bolt plan'
  trigger.run = { inline: 'bolt plan run demo' }
end
```
Examples

You can find examples of this pattern on GitHub.

https://github.com/topics/puppet-bolt?q=vagrant-environments&type=topics